

## Abstract

This application note discusses methods that can be used to enable low power modes on the Z8 Encore! XP F1680 Series MCU. It describes how to employ NORMAL, HALT and STOP modes to achieve varying degrees of low power consumption by enabling/disabling peripherals for additional power savings.

---

► **Note:** The source code files associated with this application note, AN0313-SC01, have been tested with ZDSII version 4.11.1.

---

## Features

The Z8 Encore! XP F1680 Series MCU offers the following power-saving features:

- Low power modes that can be set by the user
- A power control register that enables users to turn peripherals ON and OFF when not in use
- A wide operating voltage range of 1.8V to 3.6V
- Internal Precision Oscillator (IPO) with a wide range of selectable system clock frequencies
- Execution out of Program RAM

For more information, refer to the [Z16FMC Series Product Specification \(PS0250\)](#), available for download at <http://www.zilog.com>.

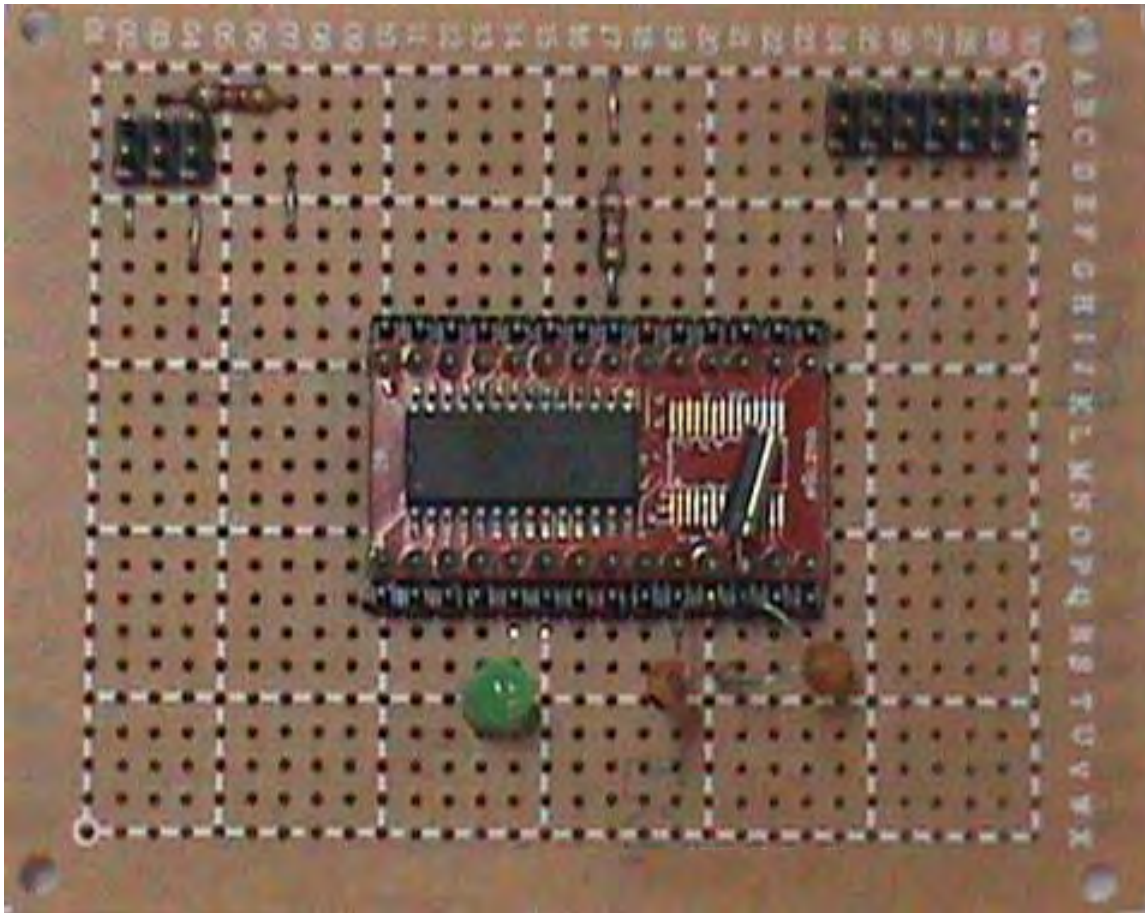
## Discussion

Zilog's Z8 Encore! XP F1680 Series MCU family is based on the advanced 8-bit eZ8 CPU core. This microcontroller is optimized for low-power applications and supports low-voltage operation (1.8V–3.6V) with extremely low NORMAL, HALT and STOP mode currents. The F1680 offers an assortment of speed and low-power options, including the option to disable and enable a number of peripherals.

A customized platform featuring a universal printed circuit board is used to obtain current measurements for this low power exercise. All factors that could have had an influence on total current consumption were removed from this customized board; however, a 32KHz

external crystal oscillator was installed to provide the lowest current consumption in STOP MODE.

Figure 1 shows the customized Z8 Encore! XP F1680 Series board and Universal PCB.



**Figure 1. The Customized Z8 Encore! XP F1680 Series Board and Universal PCB**

## **Normal Mode**

The F1680 Series MCU operates in default MCU configuration; the peripheral blocks are enabled except for a low-power operational amplifier which is disabled by default. For default values and op amp configurations, please see Zilog's companion document, the Z8 Encore! XP F1680 Series Product Specification (PS0250).

## **Program RAM**

The Z8 Encore! XP F1680 Series devices contain up to 1 KB of on-chip Program RAM. This Program RAM is mapped in the Program Memory address space beyond the on-chip Flash memory. It is entirely under user control and is meant to store the interrupt service routines of high-frequency interrupts. Because interrupts bring the CPU out of low-power

mode, it is important to ensure that interrupts that occur very often use as low a current as possible. Program RAM-based handling of high-frequency interrupts provides power savings by keeping the Flash block disabled. It is optimized for low-current operation and can be easily boot-strapped with interrupt code at power-up.

## Power Control Register

Each bit in the register listed in Table 1 disables a peripheral block by removing power from the block; the default state of the low-power operational amplifier is OFF. To use the low-power operational amplifier, clear the TRAM bit by turning it ON<sup>1</sup>. The TRAM bit enables the amplifier in STOP Mode; if the amplifier is not required in STOP Mode, disable it. Failure of the op amp to perform could result in STOP Mode currents greater than specified.



**Caution:** Clearing the TRAM bit could interfere with normal ADC measurements on the LPO output, ANA0.

**Table 1. Power Control Register 0 (PWRCTL0)**

Bits	7	6	5	4	3	2	1	0
<b>Field</b>	TRAM	Reserved		LVD/VBO	TEMP	Reserved	COMP0	COMP1
<b>Reset</b>	1	0		0	0	0	0	0
<b>R/W</b>	R/W	R/W		R/W	R/W	R/W	R/W	R/W
<b>ADDR</b>	F80H							

Bit	Description
7	<b>TRAM</b> 0 = Low-Power Operational Amplifier is enabled; also applicable to STOP Mode. 1 = Low-Power Operational Amplifier is disabled.
6:5	Reserved.
4	<b>LVD/VBO (Low-Voltage Detection/Voltage Brownout Detector Disable)</b> 0 = LVD/VBO Enabled 1 = LVD/VBO Disabled. The LVD and VBO circuits are enabled or disabled separately to minimize power consumption in low-power modes. The LVD is controlled only by the LVD/VBO bit in all modes. The VBO is set by the LVD/VBO bit as well as the VBO_AO bit of Flash Option bits at Program Memory Address 0000H.
3	<b>TEMP (Temperature Sensor Disable)</b> 0 = Temperature Sensor Enabled. 1 = Temperature Sensor Disabled.
2	Reserved.

1. If peripherals are not in use, the user can turn off the peripheral bit in all modes to reduce power consumption.

---

1	<b>COMP0 (Comparator 0 Disable)</b> 0 = Comparator 0 is Enabled; also applicable to STOP Mode. 1 = Comparator 0 is Disabled.
0	<b>COMP1 (Comparator 1 Disable)</b> 0 = Comparator 1 is Enabled; also applicable to STOP Mode. 1 = Comparator 1 is Disabled.

---

### HALT Mode

Executing the HALT instruction places the device into HALT mode, which manifests the following operating characteristics:

- The primary oscillator is enabled and continues to operate
- The system clock is enabled and continues to operate
- The program counter (PC) stops incrementing
- If enabled, the internal RC oscillator of the WDT continues to operate
- If enabled, the WDT continues to operate
- If enabled, the 32kHz secondary oscillator for Timers continues to operate
- All other on-chip peripherals continue to operate

The eZ8 CPU can be brought out of HALT mode by any of the following operations:

- Timer timeout (Interrupt or Reset)
- Interrupt (if enabled)
- Watchdog
- Power-On Reset
- Voltage Brownout Reset
- External RESET pin assertion

---

► **Note:** You can place the device into HALT mode if the system does not have a process to execute; however, the peripherals can continue to operate and wait for an interrupt to bring them out of HALT mode.

---

### STOP Mode

Executing the eZ8 CPU's STOP instruction places the device into STOP Mode. In STOP Mode, the operating characteristics are:

- 
- The primary crystal oscillator and the internal precision oscillator are stopped. XIN and XOUT, if previously enabled, are disabled; and if previously enabled for port function, PA0/PA1 reverts to the states programmed by the GPIO registers.
  - The system clock is stopped.
  - The eZ8 CPU is stopped.
  - The program counter (PC) stops incrementing.
  - The Watchdog Timer's internal RC oscillator continues operating if enabled by the Oscillator Control Register.
  - If enabled, the Watchdog Timer (WDT) logic continues operating.
  - If enabled, the 32kHz secondary oscillator continues operating.
  - If enabled for operation in STOP Mode, the Timer logic continues to operate with a 32kHz secondary oscillator as the Timer clock source.
  - If enabled for operation in STOP Mode by the associated Flash Option Bit, the VBO protection circuit continues operating. The low-voltage detection circuit continues to operate if it is enabled by the Power Control Register.
  - The Low-Power Operational Amplifier and comparator continue to operate if they are enabled by the Power Control Register.
  - All other on-chip peripherals are idle and powered down.

When the device is in STOP Mode, a Stop Mode Recovery is initiated by each of the following:

- A Watchdog Timer time-out
- A GPIO Port input pin transition on an enabled Stop Mode Recovery source
- An interrupt from a timer or comparator enabled for STOP Mode operation

The low-voltage detection circuitry on the F1680 device features the following:

- The low-voltage detection threshold level is user-defined
- The device generates an interrupt when the supply voltage drops below a user-defined level

---

► **Note:** If the system does not have a process to execute, the eZ8 CPU should be placed into STOP Mode and await any transition in the Stop Mode Recovery assignment pin to bring it out of STOP Mode.

---

# Enabling Low Power Modes with the Z8 Encore! XP F1680 Series MCU

## Application Note



**Table 2. Current and Power Consumption in NORMAL, HALT and STOP Modes**

Mode	Current Consumption (mA)	Power (mW)	Condition (3.0V)
NORMAL Execution from Flash	5.792	17.376	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D; all peripherals enabled.
	5.783	17.349	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D, LPOA disabled; all other peripherals enabled.
	5.772	17.316	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D; LVD/VBO disabled, all other peripherals enabled.
	5.737	17.211	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D; Temperature Sensor disabled, all other peripherals enabled.
	5.604	16.812	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D; Comparator disabled, all other peripherals enabled.
	5.542	16.626	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = D; all peripherals disabled.
NORMAL Execution from PRAM	3.628	10.884	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; all peripherals enabled.
	3.621	10.863	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; LPOA disabled, all other peripherals enabled.
	3.607	10.821	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; LVD/VBO disabled, all other peripherals enabled.
	3.581	10.743	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; Temperature Sensor disabled, all other peripherals enabled.
	3.462	10.386	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; Comparator disabled, all other peripherals enabled.
	3.406	10.218	$F_{SYSCLK}=11.0592\text{MHz}$ IPO, PRAM = E; all peripherals disabled.

**Notes:**

- The term *peripherals* refers to the Op Amps, LVD/VBD, Temp Sensor, Comp 0 and Comp 1.
- Measurements are not in cumulative order, but instead are individual measurements in condition and mode.
- The values in this table were measured using a microammeter. To determine more exact values, use a nanoammeter.

**Table 2. Current and Power Consumption in NORMAL, HALT and STOP Modes (Continued)**

Mode	Current Consumption (mA)	Power (mW)	Condition (3.0V)
HALT	2.667	8.001	F <sub>SYSCLK</sub> =11.0592MHz IPO; all peripherals enabled including VBO, WDT, T0 and T1.
	2.421	7.264	F <sub>SYSCLK</sub> =11.0592MHz IPO; WDT, T0 and T1 enabled, all other peripherals disabled.
	2.419	7.257	F <sub>SYSCLK</sub> =11.0592MHz IPO; T0 and T1 enabled, all other peripherals disabled.
	2.367	7.101	F <sub>SYSCLK</sub> =11.0592MHz IPO; WDT enabled, all other peripherals disabled.
	2.365	7.095	F <sub>SYSCLK</sub> =11.0592MHz IPO; all peripherals disabled.
STOP	0.006	0.018	WDT, T0 and T1 enabled; all other peripherals disabled.
	0.004	0.012	T0 and T1 enabled; all other peripherals disabled.
	0.002	0.006	WDT enabled; all other peripherals disabled.
	<0.001	<0.003	All peripherals disabled.

Notes:

- The term *peripherals* refers to the Op Amps, LVD/VBD, Temp Sensor, Comp 0 and Comp 1.
- Measurements are not in cumulative order, but instead are individual measurements in condition and mode.
- The values in this table were measured using a microammeter. To determine more exact values, use a nanoammeter.

## Hardware Architecture

To minimize power consumption when the system is not in use, the F1680 MCU is equipped with a *low power modes* option with which the user can place the MCU into STOP and HALT modes. The capability to control peripherals can add further power savings. The Power Control Register allows the user to disable or enable power in unused peripherals for additional power reduction. For a visual representation of the op amp, LVD, VBO, temperature sensor, comparators and peripherals that the Power Control Register can control, see the architectural diagram in [Appendix A](#) on page 13.

## Software Implementation

The reference design discussed in this application note uses ZDSII v4.11.0 and the Z8 Encore! XP F1680 Development Kit to simulate the STOP and HALT low-power modes, while controlling the peripherals with the Power Control Register. In this design, the objective is to implement these low-power modes using the blinker program.

First, configure the LVD/VBO to be OFF during STOP and HALT modes. The following code segment demonstrates a placement of the value 0xF7 into Flash Option Register 1 to turn off VBO in Stop Mode; the PRAM is used as Program RAM.

```
#include <ez8.h>
```

---

## Enabling Low Power Modes with the Z8 Encore! XP F1680 Series MCU

### Application Note



```
FLASH_OPTION1 = 0xF7; //VBO_AO=OFF; PRAM=Enabled
FLASH_OPTION2 = 0xFF; //Default user flash option2
```

Next, use the IPO by placing 0xC0 into OSCCTL1 to serve as the clock source, as follows:

```
OSCCTL0 = 0x8A0; //Use Internal Clock F=11.0592 MHZ
OSCCTL1 = 0xC0; // use IPO to Drive System Clock
```

Disable the Timers if they are not required in your design and instead use the peripheral timer clock source. ADC and I<sup>2</sup>C can also be disabled to reduce power consumption by setting ADCCTL0 = 0x00 and I2CCTL = 0x00. The control registers that govern the other peripherals can be used to attain additional power savings, and power in the peripheral block can be disabled via the Power Control Register, as shown below.

```
PWRCTL0 = 0xFF; //TRAM; LVD/VBO; TEMP; COMP0; COMP1 are turned off
```

Setting or clearing each bit of the Power Control Register enables or disables power in the peripheral block. PWRCTL0 can be initialized in any part of the source code.

To execute in Program RAM (PRAM) during NORMAL Mode, the determination was to insert the #pragma PRAM statement above the void main(void) statement, as shown:

```
#pragma PRAM
Void main(void)
{
.
.
.
}
```

Example 1 below turns the LED ON and OFF in PORT C and goes into STOP/HALT mode after 50 cycles.

#### Example 1. Blinker Program with STOP Mode

```
for(x=0;x<100;x++) {
for(i=0;i<0xFFFF;i++);
PCOUT = ~PCOUT;
}
PCOUT =~0x00;
asm("STOP");
while(1);
```



The `asm( "STOP" )` command places the device into STOP Mode. The device can be brought out of STOP Mode by means of a Stop Mode Recovery. Configure this Stop Mode Recovery by tying the GPIO interrupt at pin PA2. Any logic transition at pin PA2 can bring the device out of STOP Mode, as shown by the following code and Figure 2.

```
PADD = 0x04;  
PAAF = 0x00;  
PAOC = 0x00;  
PAHDE = 0x00;  
PAPUE = 0x04;  
PASMRE = 0x04;
```

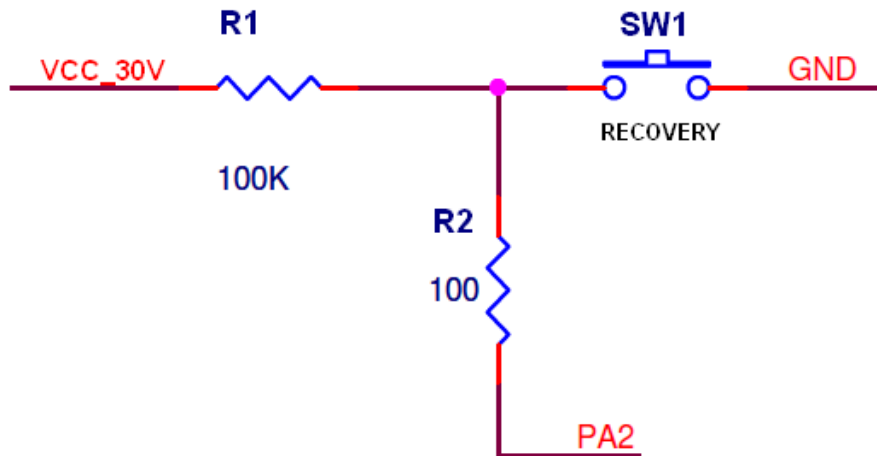


Figure 2. Recovery from STOP Mode at Pin PA2

The Blinker program used in Example 1 can also be used to place the F1680 device into HALT mode, as shown in Example 2.

**Example 2.** Blinker Program with HALT mode

```
for(x=0;x<100;x++) {  
  for(i=0;i<0xFFFF;i++);  
  PCOUT = ~PCOUT;  
}  
PCOUT = ~0x00;  
asm( "HALT" );  
while(1);
```

The `asm( "HALT" )` command places the device into HALT mode. The device can be brought out of HALT Mode by a reset or a Stop Mode Recovery and by using a RESET assertion, as shown in Figure 3.



Figure 3. Recovery from HALT Mode

To review the entire codeset for the with low power mode Blinker program, see [Appendix B](#) on page 14.

## Required Equipment

The equipment listed below is used to build the Blinker application.

1. F1680 Series Development Kit featuring the F1680 MCU
2. ZDSII Z8 Encore 4.11.0
3. Multimeter
4. Power Supply

## Setup

Figures 4 and 5 show a simple block diagram and an actual image of the Blinker application setup.

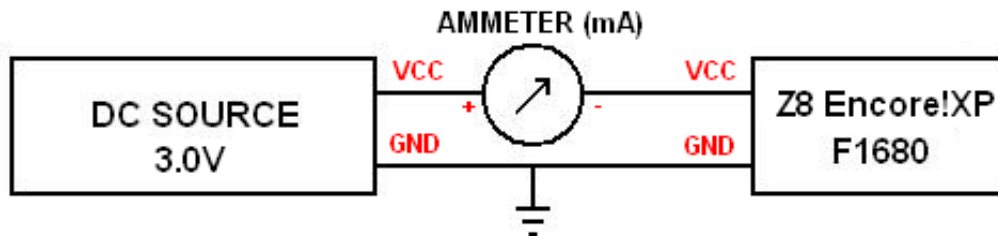


Figure 4. Blinker Application Setup, Block Diagram

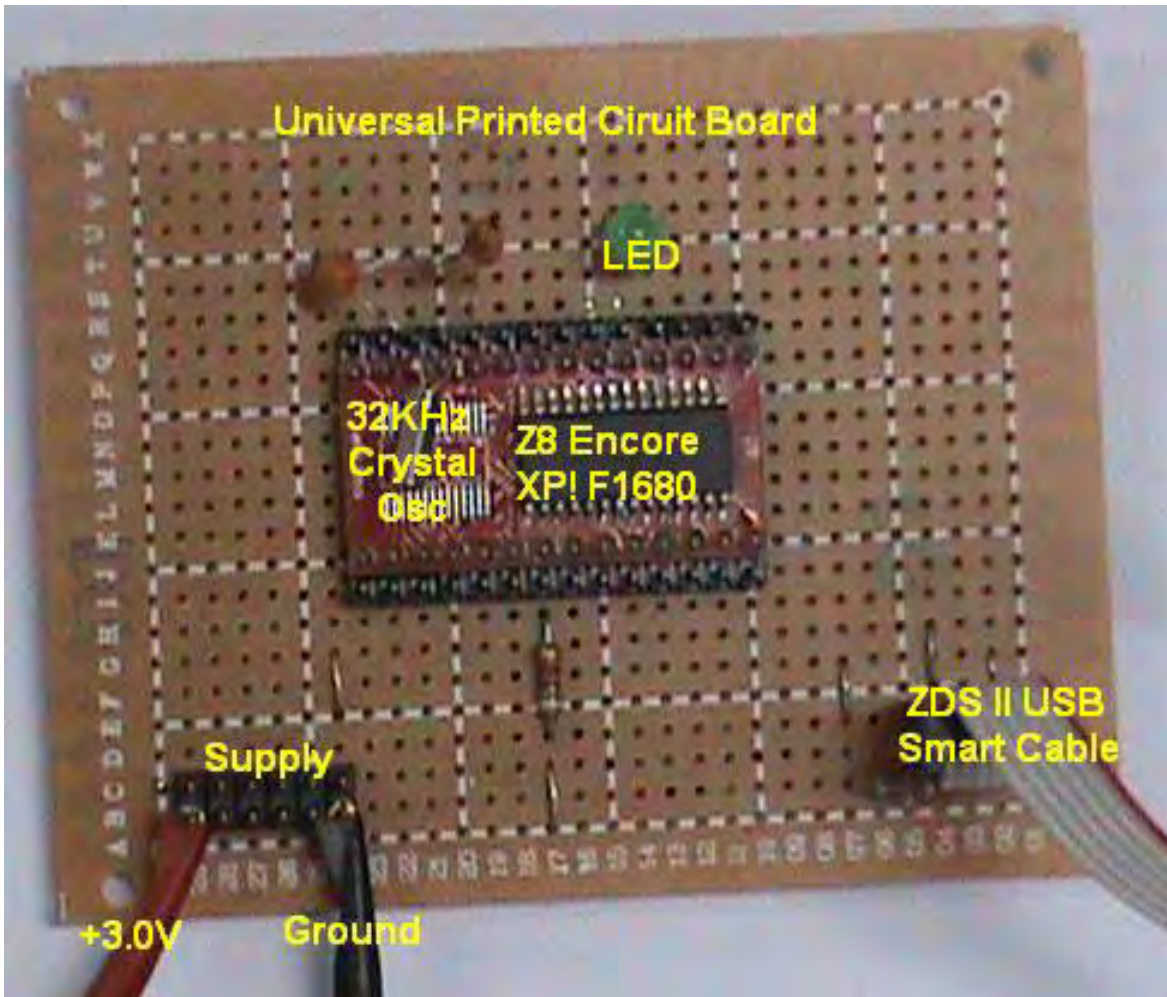


Figure 5. Blinker Application Setup, Actual

## Results

Each mode of operation results in a significant reduction in power consumption. See [Table 2](#) on page 6 for the measurement results showing current and power usage under different modes and conditions.

## Summary

This application note provides a blueprint for utilizing the low power features of the Z8 Encore! XP F1680 Series MCU. A simple hardware architecture and a simple Blinker program enable different low power mode possibilities. The Blinker software is modular and easy to customize for any low power application.

---

## References

The following documents associated with the Z8 Encore! XP F1680 device are available on [www.zilog.com](http://www.zilog.com).

- [Z8 Encore! XP F1680 Series Product Specification \(PS0250\)](#)
- [Z8 Encore! XP F1680 28-pin Development Kit User Manual \(UM0203\)](#)

## Appendix A. Z8 Encore! XP F1680 Block Diagram

Figure 7 shows the architecture of the Z8 Encore! XP F1680 MCU, complete with peripheral blocks.

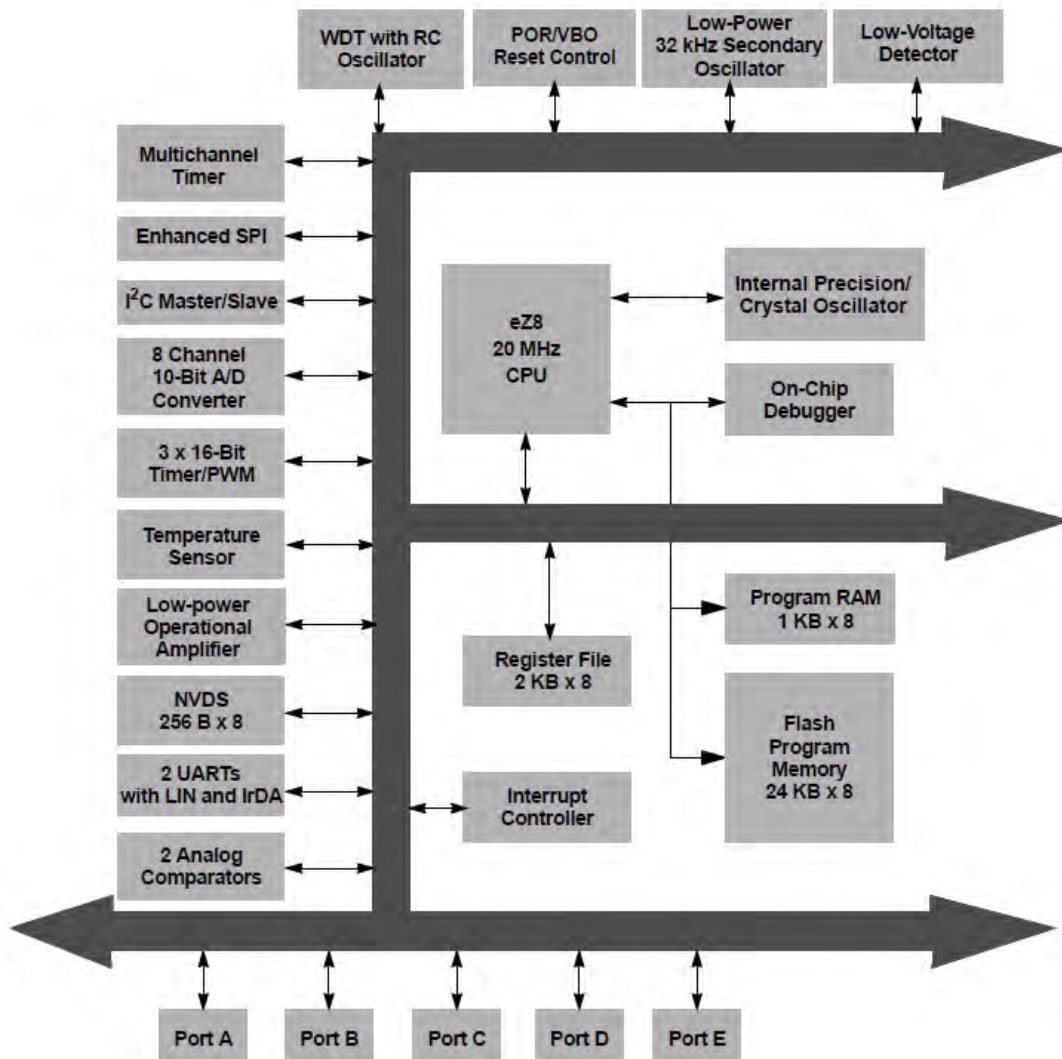


Figure 6. Z8 Encore!XP F1680 Block Diagram

---

## Appendix B. Low Power Modes Source Code

```
//LED at PORTC Blinker Program with Low Power Modes
/
*****
* This is compiled using ZDSII Z8 Encore 4.11.0
* Copyright (C) 1999-2008 by Zilog, Inc. ALL RIGHTS RESERVED.
* The source code in this file was written by an authorized
* Zilog employee or a licensed consultant. The source code has
* been verified to the fullest extent possible. Permission to
* use this code is granted on a royalty-free basis. However
* users are cautioned to authenticate the code contained herein.
* Zilog DOES NOT GUARANTEE THE VERACITY OF THE SOFTWARE.
*****
/
#include <ez8.h>

FLASH_OPTION1 = 0xF7;
FLASH_OPTION2 = 0xFF;

#pragma PRAM
void main (void) //WDT ON |T0 & T1 enable &
                //Everything OFF, Running on Stop Mode
{
    unsigned int delay = 5000;
    unsigned int x, i;
    DI();
//WDTH = 0x55;    //WDT Unlock Sequence
//WDTH = 0xAA;
//WDTH = 0xFF;    //WDT Timer
//WDTL = 0xFF;    //Max = 0xFFFF (6.55 sec)

    LEDEN = 0x00;
    LEDLVLH = 0x00;
    LEDLVLL = 0x00;

    PADD = 0x04;    //PA as Output MODE
    PAAF = 0x00;
    PAOC = 0x00;
    PAHDE = 0x00;
    PAPUE = 0x00;
    PASMRE = 0x00;
//PASMRE = 0x040; //Any logic transition on this port during STOP mode initiates Stop
                //Mode Recovery. For HALT mode, Reset assertion initiate recovery
    PAOUT = 0xFF;    //PA Data FFH

    PBDD= 0x00;    //PB as Output MODE
    PBAF = 0x00;
    PBOC = 0x00;
    PBHDE = 0x00;
    PBPUE = 0x00;
    PBSMRE = 0x00;
    PBOUT = 0xFF;    //PB Data FFH
```

---

## Enabling Low Power Modes with the Z8 Encore! XP F1680 Series MCU Application Note



---

```
PCDD = 0x00;    //PC as Output MODE
PCAF = 0x00;
PCOC = 0x00;
PCPUE = 0x00;
PCHDE = 0x00;
PCSMRE = 0x00;
PCOUT = 0xFF;  //PC Data FFH

OSCCTL0 = 0xE7; //Unlock sequence
OSCCTL0 = 0x18;
OSCCTL0 = 0x80;
// OSCCTL0 = 0x80|0x20;

while(delay--);

OSCCTL1 = 0xE7;
OSCCTL1 = 0x18;
OSCCTL1 = 0xC0; //use IPO to Drive System Clock

//PWRCTL0 = 0x00; //LPO, VBO, TEMP, COMP are enabled
PWRCTL0 = 0x9B; //LPO, VBO, TEMP, COMP are disabled

TOCTL0 = 0x00; //Set up T0 & T1 Timers
T1CTL0 = 0x00; //Driven by external 32Khz CRYSTAL
T0CTL1 = 0x39;
T1CTL1 = 0x39;
T0CTL2 = 0x00;
T1CTL2 = 0x00;
T0CTL1 |= 0x80;
T1CTL1 |= 0x80;
EI();

for(x=0;x<100;x++) {
    for(i=0;i<0xFFFF;i++){
        PCOUT = ~PCOUT;
        PAOUT = ~PAOUT;
    }
}
// asm("WDT");
// asm("STOP"); //Put the device in STOP mode
//Uncomment this for STOP mode
asm("HALT"); //Put the device in HALT mode
//Uncomment this for HALT mode
while(1);
}
```

---

## Customer Support

To share comments, get your technical questions answered, or report issues you may be experiencing with our products, please visit Zilog's Technical Support page at <http://support.zilog.com>.

To learn more about this product, find additional documentation, or to discover other facts about Zilog product offerings, please visit the Zilog Knowledge Base at <http://zillog.com/kb> or consider participating in the Zilog Forum at <http://zillog.com/forum>.

This publication is subject to replacement by a later edition. To determine whether a later edition exists, please visit the Zilog website at <http://www.zilog.com>.



**Warning:** DO NOT USE THIS PRODUCT IN LIFE SUPPORT SYSTEMS.

---

### LIFE SUPPORT POLICY

ZILOG'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS PRIOR WRITTEN APPROVAL OF THE PRESIDENT AND GENERAL COUNSEL OF ZILOG CORPORATION.

#### As used herein

Life support devices or systems are devices which (a) are intended for surgical implant into the body, or (b) support or sustain life and whose failure to perform when properly used in accordance with instructions for use provided in the labeling can be reasonably expected to result in a significant injury to the user. A critical component is any component in a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system or to affect its safety or effectiveness.

#### Document Disclaimer

©2011 Zilog, Inc. All rights reserved. Information in this publication concerning the devices, applications, or technology described is intended to suggest possible uses and may be superseded. ZILOG, INC. DOES NOT ASSUME LIABILITY FOR OR PROVIDE A REPRESENTATION OF ACCURACY OF THE INFORMATION, DEVICES, OR TECHNOLOGY DESCRIBED IN THIS DOCUMENT. ZILOG ALSO DOES NOT ASSUME LIABILITY FOR INTELLECTUAL PROPERTY INFRINGEMENT RELATED IN ANY MANNER TO USE OF INFORMATION, DEVICES, OR TECHNOLOGY DESCRIBED HEREIN OR OTHERWISE. The information contained within this document has been verified according to the general principles of electrical and mechanical engineering.

Z8, Z8 Encore!, Z8 Encore! XP and ZMOTION are trademarks or registered trademarks of Zilog, Inc. All other product or service names are the property of their respective owners.