



**ZAURA™ RF Wireless Technology**

# **ZAURA RF Module Shell**

**User Manual**

UM023502-0911

## Revision History

Each instance of Revision History reflects a change to this document from its previous version. For more details, refer to the corresponding pages and appropriate links in the table below.

<b>Date</b>	<b>Revision Level</b>	<b>Description</b>	<b>Page No.</b>
Sep 2011	02	Remote command moved to list of default commands from list of optional commands. Minor additional updates throughout.	<a href="#">8</a>
Feb 2011	01	Original issue.	All

## Safeguards

The following precaution must be observed when working with the devices described in this document.



**Caution:** Always use a grounding strap to prevent damage resulting from electrostatic discharge (ESD).

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## Shell Overview

The ZAURA RF Wireless Module Shell is a command line interpreter that can be used to control ZAURA RF Wireless nodes over an RS-232 (UART) connection. The Shell is preloaded on the ZAURA RF Wireless Module when shipped from the factory.

Users interact with the Shell through a terminal emulator, such as HyperTerminal, which should typically be configured with 57600 baud, no parity, 1 stop bit, and no flow control. Users can control remote notes as well, using the `REMOTE` command (similar to `telnet`).

The Shell is a part of the ZAURA RF Wireless Library and includes application programming interfaces to implement the different Shell commands. The Shell API provides six mandatory commands that will exist on all substantiations. The Shell may contain an additional 24 commands which may be employed either as built-in optional functions or as defined by your application. For more information about how to implement and incorporate the Shell into your application, please refer to the [ZAURA RF Wireless Library Reference Manual \(RM0060\)](#).

The following sections cover the usage of each of the commands that are built into to the Shell. Each command is shown along with a set of mandatory and optional parameters. Parameters are shown in italics, and optional parameters are enclosed in angular brackets *<like this>*. Shell command names are case-insensitive, so the commands `Addr`, `addr` and `aDDr` are equivalent. However, case sensitivity may apply to the parameters. For example, the `tx ff hello` command will send a different string than `tx ff HELLO`. Unless stated otherwise, all numeric parameters passed to the shell must be specified in hexadecimal format. Similarly, all numeric values returned from the shell are displayed as hexadecimal values. For example, issuing the command `addr 23` sets the node address of the ZAURA RF Module to the hexadecimal value `0x23` (35 decimal).

Table 1 lists the default ZAURA RF Wireless Module Shell commands and references the page each is described on in this manual.

**Table 1. Default ZAURA RF Wireless Module Shell Commands**

<b>Command</b>	<b>Described On Page #</b>
?	<a href="#">4</a>
read	<a href="#">5</a>
write	<a href="#">6</a>
regs	<a href="#">7</a>
remote	<a href="#">8</a>
rvns	<a href="#">10</a>
wvns	<a href="#">11</a>

Table 2 lists the optional ZAURA RF Wireless Module Shell commands and references the page each is described on in this manual.

**Table 2. Optional ZAURA RF Wireless Module Shell Commands**

<b>Command</b>	<b>Described On Page #</b>
addr	<a href="#">12</a>
ch	<a href="#">13</a>
data	<a href="#">14</a>
dst	<a href="#">15</a>
echo	<a href="#">16</a>
filter	<a href="#">17</a>
ipo	<a href="#">18</a>
nid	<a href="#">20</a>
pa	<a href="#">21</a>
per	<a href="#">22</a>
port	<a href="#">24</a>

**Table 2. Optional ZAURA RF Wireless Module Shell Commands (Continued)**

Command	Described On Page #
pwr	<a href="#">26</a>
reboot	<a href="#">27</a>
rsi	<a href="#">28</a>
rx	<a href="#">29</a>
sleep	<a href="#">30</a>
stats	<a href="#">31</a>
tx	<a href="#">33</a>
uecho	<a href="#">34</a>
wake	<a href="#">36</a>

## Default Shell Commands

The default Shell commands listed in Table 1 are each described in this section, complete with command syntax and examples. These Shell command descriptions begin on the next page.

?

## Help

### Syntax

?

### Example

?

### Available Commands

?

read

write

regs

rnvs

wnvs

remote

addr

ch

data

dst

echo

The `Help` command displays the list of available shell commands for this node.

## ***read***      **Read registers**

### **Syntax**

```
read ofs <len>
```

### **Example 1**

```
read 10  
D6
```

### **Example 2**

```
read 10 5  
D6 38 28 07 27
```

The `read` command displays a subset of the ZAURA RF Wireless Module register set. The *ofs* parameter specifies the zero-based offset of the first register to read. The optional *<len>* parameter specifies the number consecutive registers to read. If *<len>* is omitted, only the contents of *ofs* is displayed. All values must be specified in hexadecimal format.

The *ofs* parameter must be between 0x00 and 0x1F.

## ***write***      **Write registers**

### **Syntax**

```
write ofs data
```

### **Example**

```
write 16 aabbccdd  
AA BB CC DD D6
```

The `write` command is used to modify one or more ZAURA RF Wireless Module registers beginning with *ofs*. If the *data* parameter specifies a single 8-bit value, only register *ofs* is modified. Otherwise, subsequent data values will be written to sequential registers.



**Caution:** Altering the contents of the radio registers can disrupt – or even disable – all communication within the ZAURA RF Wireless cell and cause the application to stop working properly. The `write` command is typically only used for diagnostic purposes.

---

## ***regs***      **Read all 32 radio registers**

### **Syntax**

```
regs
```

### **Example**

```
regs  
70 8C 03 03 0C C0 74 5C 3A 8F 72 25 38 C8 13 00  
D6 38 38 07 29 00 AA BB CC DD F0 00 3F 23 BE 00
```

The `regs` command displays the contents of all 32 ZAURA RF Wireless radio registers. It is equivalent to issuing the command `read 0 20`.

## ***remote*** Issue command to remote node(s)

### **Syntax**

```
remote cmd <param>
```

### **Example 1**

```
remote addr  
local address: 1b
```

### **Example 2**

```
remote rrvs 0 6  
02 11 22 00 00 1B
```

### **Example 3**

```
remote tx ff Hello  
Rx Packet: RSSI 8A Pwr -49 dBm  
05 FF 1B 00 68 65 6C 6C 6F  
Transmit DA FF data: hello  
Done transmit
```

The `remote` command is used to transmit a shell command to the default ZAURA RF Wireless target address (DST command). The command is not echoed on the remote terminal. In Example 3 above, the local node will send a request to the remote node to issue a transmit request of "Hello" to the broadcast address. The Remote node's command interpreter will process the shell command (`tx ff Hello`) and transmit the packet. When the local node receives the transmitted packet from the remote node, it displays the received packet from the remote node.

Prior to initiating a remote shell command, the default ZAURA RF Wireless Module target address should be set to a unique address. If the broadcast address (`ff`) is used, the node issuing the `remote` console command

could potentially be flooded with responses unless there is only one other ZAURA RF Wireless node in the same cell.

- 
- ▶ **Note:** Any shell command can be executed remotely. However, be aware that side effects may prevent further communication. For example, changing the RF channel used by a remote node will prevent the node that issued the remote command from receiving any console output from the target.

Executing a command on the Shell of a remote node, and the display of output generated by such a command through the local Shell when using the remote command, is only possible if both nodes are configured to use the DA\_SA\_CTRL frame format.

---

## ***rnvs***      **Read one or more configuration Flash information bytes**

### **Syntax**

```
rnvs ofs <len>
```

### **Example**

```
rnvs 0 9  
04 11 22 33 44 23 01 00 03
```

The *rnvs* command displays a subset of the ZAURA RF Wireless Module configuration information stored in Flash. The *ofs* parameter specifies the 0-based offset of the first location to read. The optional *<len>* parameter specifies the number consecutive memory addresses to read. If *<len>* is omitted only the contents of *ofs* is displayed. All values must be specified in hexadecimal format.

The *ofs* parameter must be between 0x00 and 0xFF.

## ***wnvs*** Write one or more configuration Flash information bytes

### **Syntax**

*wnvs ofs data*

### **Example**

```
wnvs 2 1234  
12 34
```

The `wnvs` command is used to modify one or more Flash memory locations that contain ZAURA RF Wireless parameters. The *ofs* parameter specifies the first location to modify. If the *data* parameter specifies a single 8-bit value, only the memory location at *ofs* is modified. Otherwise, subsequent data values will be written to sequential memory locations.

## **Optional Shell Commands**

The optional Shell commands listed in [Table 2](#) on page 2 are each described in this section, complete with command syntax and examples. These optional Shell command descriptions begin on the next page.

## ***addr***      **Set/Get local address**

### **Syntax**

```
addr <addr>
```

### **Example 1**

```
addr  
local address: 23
```

### **Example 2**

```
addr 7F
```

If the `addr` command is issued without any parameters, the current ZAURA RF Wireless node address is displayed. If the `<addr>` parameter is specified and it is between `0x01` and `0xFE`, the local RF address is modified and the RF parameters in Flash are updated.

## **ch**      **Set/Get current channel**

### **Syntax**

```
ch <NewCh>
```

### **Example 1**

```
ch  
Currently using channel 0
```

### **Example 2**

```
ch 3  
Switching to Channel 3  
Currently using channel 3
```

If the <NewCh> parameter is omitted, the current RF channel is displayed. If the <NewCh> parameter is specified and valid, the radio is configured for the new channel and the RF parameters stored in Flash are updated. After the RF channel is altered, the node will not be able to communicate with any nodes on the previous channel. This command effectively switches the ZAURA RF Wireless node into a different cell. If the <NewCh> parameter is specified but invalid, the radio configuration is not modified. Refer to the ZAURA RF Wireless Module product user guide that describes your particular module to determine the valid channels.

## *data*      **Link console to RF I/O**

### **Syntax**

data

### **Example 1**

data

Entering DATA mode

console input is sent to remote peer(s) until exit data mode via++

Exiting DATA mode

The ZAURA RF Wireless Module console features two modes of operation: Command Mode and Data Mode. By default, the console is configured for Command Mode, meaning that characters received over UART0 are processed by the local command interpreter. However, when the console is switched to Data Mode via this command, data received over UART0 is transmitted to the default ZAURA RF Wireless Module target address (DST command). If the remote device is also operating in data mode, it sends the data received from the radio over UART0. This action allows bridging to/from the local UART via RF to/from the remote UART, e.g.:

Local UART ↔ RF ↔ remote UART

To exit Data Mode and return to Command Mode, press the two consecutive escape characters.

- 
- ▶ **Notes:** The default ZAURA RF configuration file uses ++ as the escape sequence, but the value of the ZAURA\_RF\_DataEscChar variable can be modified to specify a different escape character.

While the ZAURA RF Wireless Module console operates in Data Mode, the command interpreter is still able to process commands issued from remote nodes.

---

## ***dst***      **Set/Get Destination for other commands**

### **Syntax**

`dst <addr>`

### **Example 1**

```
dst
RF target address: FF
```

### **Example 2**

```
dst 6B
```

The `dst` console command is used to display or modify the default ZAURA RF Wireless Module target address, `ZAURA_RF_Dest`. This `ZAURA_RfDest` address is the implied target of the `remote`, `data`, `echo` and `per` console commands. After every Power-On Reset, the `dst` address is reset to the default value of the `ZAURA_RfDest` configuration variable defined in `ZAURA_RF_Conf.c`.

## ***echo*** Ping/pong message between nodes

### **Syntax**

```
echo <message>
```

### **Example 1**

```
echo
```

### **Example 2**

```
echo "hello world"  
Tx 1 Rx 1 'hello world'  
Tx 2
```

The `echo` command is used to initiate a ping-pong test between two nodes. Prior to issuing the `echo` command on both nodes, use the `dst` console command to specify the ZAURA RF Wireless nodes address of the peer device.

On the first node, enter the `echo` command without any parameters to configure the node as the initial responder (pong). On the second device, issue the `echo` command and supply an arbitrary `<message>` to transmit to the peer (ping). If the remote receives the `<message>`, it will echo it back to the transmitter. Upon receipt of the echo, the transmitter echoes it back to the remote device. This process continues until the packet is lost (one side will show a Tx message but not an Rx message) or a key is pressed in the terminal program to exit the test.

## ***filter***      **Set/Get address filter**

### **Syntax**

```
filter <setting>
```

### **Example 1**

```
filter  
Rx filter level 3
```

### **Example 2**

```
filter 1
```

The `filter` command is used to display or modify the current setting of the radio's address filter. If the `filter` command is issued without any parameters, the current filter value is displayed. If this command is issued with a `<setting>` parameter, the radio's receive filter is modified and the new `filter` setting is stored in Flash. The filter can include broadcast packets (a filter value of 3) or exclude broadcast packets (a filter value of 1).

## *ipo*      **Set/Get Oscillator control configuration variable**

### Syntax

```
ipo <index>
```

### Example 1

```
ipo
IPO frequency 2 (2764800 Hz)
```

### Example 2

```
ipo 0
Rebooting...
```

```
ZAURA RF Wireless v1.10a Build 11081801
```

```
-----
FW checksum 7C57
```

This `ipo` console command can be used to modify the `ZAURA_RF_OscCtrl1` configuration variable. The value of the `ZAURA_RF_OscCtrl1` variable determines the system clock frequency of the Z8F2480 MCU's Internal Precision Oscillator (IPO). The ZAURA RF Wireless Module library can be used with IPO frequencies from 1.3842MHz to 11.0592MHz.

If the `ipo` command is issued without any parameters, the current IPO frequency is displayed. If the `<index>` parameter is specified and contains a value between 0 and 3, then the value of the `OscCtrl1` configuration variable in Flash is updated and the system performs a reset procedure to re-initialize all peripherals with the new system clock frequency.

The UART baud rate will be modified if the IPO frequency is changed to or from the 1.3.824MHz frequency, as indicated in Table 3.

**Table 3. UART Baud Rate per IPO Index**

<b>IPO Index</b>	<b>System Clock (MHz)</b>	<b>UART Baud Rate (kbps)</b>
0	11.0592	57.6
1	5.5296	57.6
2	2.7648	57.6
3	1.3824	28.8

The lower the IPO frequency, the less current the ZAURA RF Wireless Module will consume. However, it will also be more difficult to keep pace with a peer device running at a higher IPO frequency and sending bursts of data. Zilog recommends operating peer devices at the same IPO frequency.

## *nid*      **Set/Get Network ID**

### **Syntax**

`nid <setting>`

### **Example 1**

```
nid
Network ID: 1122
```

### **Example 2**

```
nid B2C4C6E8
```

The `nid` console command displays or modifies the ZAURA RF Wireless Module network identifier. If the `nid` command is issued without any parameters, the current value of the `nid` is displayed. If the `<setting>` parameter is specified and is between 1 and 4 bytes in length, the radio is reconfigured and the new `nid` is stored in Flash. If the `nid` is invalid, the radio is not reconfigured and Flash parameters are not modified.

## ***pa***      **transmit constant preambles**

### **Syntax**

```
pa <dummy>
```

### **Example 1**

```
Pa  
OOOO
```

### **Example 2**

```
Pa xx  
xOxOx
```

The `pa` console command is used to force the transmitter to emit a stream of constant preambles on the current RF channel at the current Tx power level setting. If the `pa` command is issued without any parameters, then the radio will continuously emit preambles until a key is pressed on the terminal program. If a parameter is specified, then regardless of the value of the parameter, the radio will emit preambles for a period of 1 second and then stop sending preambles for a period of 1 second. This cycle repeats such that the radio emits preambles with a 50% duty cycle at 0.5Hz. While transmitting preambles, the node running the `pa` command may interfere with nearby RF communications and could even prevent other nodes from being able to communicate at all.

As the `pa` command operates, it will display a character on the console every second. An “O” is displayed if the radio is emitting preambles, and an “x” is displayed when it is silent. The `pa` command terminates when a key is pressed on the console terminal.

## *per*      **Send bursts of 100 test packets to target**

### Syntax

*per* <*addr*>

### Example 1

Per

Target 7F should be running 'RX' command

Polling 7F Index 0000 RxCount 100 on cycle 0

Polling 7F Index 0001 RxCount 100 on cycle 1

Polling 7F Index 0002 RxCount 100 on cycle 2

### Example 2

*per* 23

Target 23 should be running 'RX' command

Polling 23 Index 0000 ... no response

Polling 23 Index 0000 ... no response

Polling 23 Index 0000 ... no response

The *per* and *rx* console commands are intended to be used together to test the performance of the link. The node that runs the *per* command sends bursts of 100 packets to the target node. This target node may be explicitly identified using the <*addr*> parameter. If an <*addr*> parameter is not specified, the performance test frames will be sent to the default ZAURA RF Wireless Module target address `RfDest` (DST command).

After transmitting 100 packets, the node running the *per* command polls the target for a response frame. The objective is to determine how many performance test frames the target actually received since the last time it was polled. If there are no link errors, the target response should indicate that 100 packets were received. If a response is received within approximately 100ms, the number of test packets received by the remote target is displayed. In this instance, the transmitter increments an index counter

and sends the next block of 100 packets. If a poll response is not received after the 100ms time-out, the transmitter will resend the poll request.

This process continues until the operator presses a key on the terminal program to end the performance test.

## **port**      **Set/Get GPIO pin state**

### **Syntax**

Port *reg* <*op value*>

### **Example 1**

```
port e
Port_E initially 20 now 20
```

### **Example 2**

```
port e = 40
Port_E initially 20 now 40
```

### **Example 3**

```
port e ^ 60
Port_E initially 40 now 20
```

The `port` console command can be used to manipulate GPIO output pins. The `port` command requires at least one parameter, *reg*, that specifies which Z8F2480 GPIO port is being targeted. Valid values of *reg* are `a` through `e`, which target the GPIO output registers PAOUT through PEOUT. If the <*op value*> parameters are omitted, then the current setting of the GPIO output port is displayed.

The <*op value*> parameters identify a bit-wise operator to use with the current value of the port register and the *value* parameter. Valid `port` operators and their usage are shown in Table 4.

**Table 4. port Operator Definitions**

<b>Operator (op)</b>	<b>Definition</b>
=	Assigns value to the target GPIO output port. Equivalent to the “C” statement: “PxOUT = value;”

**Table 4. port Operator Definitions (Continued)**

Operator (op)	Definition
	Performs a bit-wise OR using the current value of the output port register and the value parameter. Equivalent to the “C” statement “PxOUT  = value;”
&	Performs a bit-wise AND using the current value of the output port register and the value parameter. Equivalent to the “C” statement “PxOUT &= value;”
^	Performs a bit-wise XOR using the current value of the output port register and the value parameter. Equivalent to the “C” statement “PxOUT ^= value;”



**Caution:** Use the `port` command with caution, because modifying port pins can cause unexpected behavior.

## *pwr*      **Set/Get Transmit Power level**

### Syntax

Pwr <setting>

### Example 1

Pwr  
Tx power level 0 (13 dBm)

### Example 2

pwr 3

<b>pwr Setting</b>	<b>dBm Value</b>
0	13 dBm
1	10 dBm
2	7 dBm
3	4 dBm
4	1 dBm
5	-2 dBm
6	-5 dBm
7	-8 dBm

The *pwr* console command is used to display or modify the transmit power level of the ZAURA RF Wireless Module radio. If the *pwr* command is issued without any parameters, the current transmit power level is displayed. If this command is issued with a <setting> parameter and the value is valid (less than 8), the radio's transmit power level is modified and the new setting is stored in Flash. If the <setting> parameter is invalid, the radio's transmit power level is not modified and the contents of `RfParams` in Flash is not modified.

## ***reboot***    **Soft reset of the node**

### **Syntax**

```
reboot
```

### **Example 1**

```
reboot
```

```
ZAURA RF Wireless v1.10a Build 11081801
```

```
-----  
FW checksum 7C57
```

After the `reboot` command is issued, the ZAURA RF Wireless node undergoes a soft reset.

## *rss*      **Read Receive Signal Strength Indicator**

### Syntax

```
rss
```

### Example 1

```
rss
--2D-- RSSI: Ave 2D (-95 dBm) Max 39 (-89 dBm), Min 00 (-105 dBm)
--2E-- RSSI: Ave 2E (-95 dBm) Max 3B (-88 dBm), Min 24 (-100 dBm)
--31-- RSSI: Ave 2E (-95 dBm) Max 38 (-90 dBm), Min 24 (-100 dBm)
--33-- RSSI: Ave 2E (-95 dBm) Max 3A (-89 dBm), Min 24 (-100 dBm)
--2B-- RSSI: Ave 2E (-95 dBm) Max 3B (-88 dBm), Min 24 (-100 dBm)
--2F-- RSSI: Ave 2E (-95 dBm) Max 3C (-88 dBm), Min 24 (-100 dBm)
--24-- RSSI: Ave 2E (-95 dBm) Max 39 (-89 dBm), Min 24 (-100 dBm)
--31-- RSSI: Ave 2E (-95 dBm) Max 39 (-89 dBm), Min 24 (-100 dBm)
```

After the `rss` command is issued, the radio is placed into receive mode and begins listening to the current channel. During this test, the RSSI level is sampled 256 times to determine the average, minimum and maximum RSSI value detected. The `rss` command then displays a message indicating the last RSSI value sampled and the average, minimum and maximum values from the most recent 256 samples. The RSSI values are also converted to the approximate receiver power level in dBm. The `rss` test terminates after a key is pressed on the console terminal program.

**rx**

## Receive mode for test packets (per command)

### Syntax

Rx

### Example 1

Rx

Waiting for packets from peer running 'PER 23' command

....\*.....

The `per` and `rx` console commands are intended to be used together to test the performance of the link. The node that runs the `rx` command (the receiver) places the radio in receive mode and waits for the node running the `per` command to send a burst of packets and then query the receiver. The receiver expects to receive a burst of 100 packets, followed by a poll request.

As the receiver receives test packets from the transmitter, it increments a packet counter. When a poll packet is received, the receiver sends a response packet to the transmitter to indicate the number of packets that have been received since the last time it was polled. If the packet count in the response is 100, the receiver displays a period (.) on the console. If fewer than 100 packet were received, an asterisk (\*) is displayed. After the receiver sends the poll response packet, it resets the packet counter to 0 and waits for the next block of 100 packets from the transmitter.

The `rx` test terminates after a key is pressed on the console terminal program.

## *sleep*      Put node to sleep

### Syntax

```
sleep
```

### Example 1

```
sleep  
Going to sleep...
```

After the `sleep` command is issued, the ZAURA RF Wireless node is placed into a low power state. The unit will remain dormant until an F2480 Stop Mode Recovery event returns the unit to normal mode. When the `sleep` command is issued in the default ZAURA RF Demo program running on the ZAURA Wireless validation board, pressing the **SW1** pushbutton or typing a character on the console terminal will reactivate the Module. When using the `sleep` command with a custom project any GPIO port pin configured as a Stop Mode Recovery source can be used to reactivate the Module.

## **stats**      **Get RF Statistics for this node**

### **Syntax**

```
stats <clr>
```

### **Example 1**

Stats

RF Statistics:

```
Rx Pkts 00000 Bytes 000000000 NoBuf 00000
Rx Ack 00001 Pause 00000 Nak 00000 Retry 00000
Tx Pkts 00001 Bytes 000000005 UR 00000 Busy 00000
Tx Ack 00000 Pause 00000 Nak 00000 Retry 00000
```

### **Example 2**

Stats clr

The `stats` console command displays a running total of the number of packets/ bytes sent and received. All values are displayed in decimal format. The statistics can be cleared by issuing the `stats clr` command.

The statistics are divided into two sections, receive (Rx) and transmit (Tx), with similar counters displayed in both groups. Table 5 describes each of these counters.

**Table 5. stats Counter Definitions**

<b>Counter</b>	<b>Definition</b>
Rx Pkts	The number of data packets received from remote devices.
Rx Bytes	A cumulative total of bytes received in the data field of all received packets (headers are not included).

**Table 5. stats Counter Definitions**

<b>Counter</b>	<b>Definition</b>
Rx NoBuf	The number of times the receiver dropped an otherwise valid packet because no receive buffers were available.
Rx Ack	The number of ACK frames received in response to all transmitted SDATA frames.
Rx Pause	The number of times a target node requested this node to PAUSE before sending another data packet.
Rx Nak	The number of SDATA frames transmitted that reached the intended target but were rejected because of an invalid sequence number.
Rx Retry	The number of SDATA packets received that required at least one retransmission.
Tx Pkts	The number of data packets transmitted to remote nodes.
Tx UR	The number of failed transmission attempts due to a transmit underrun.
Tx Busy	The number of aborted transmissions due to a busy channel (RSSI sampled above ZAURA_RF_RSSI for ZAURA_RF-CsAttempts times).
Tx Bytes	A cumulative total of bytes transmitted in the data field of all transmitted packets (header are not included).
Tx Underrun	The number of failed transmission attempts due to a transmit underrun.
Tx Ack	The number of ACK frames transmitted in response to all received SDATA frames.
Tx Pause	The number of times this node requested a PAUSE delay after crossing a low buffer threshold.
Tx Nak	The number of times this node rejected a received SDATA frame because of an invalid sequence number.
Tx Retry	The number of SDATA packets transmitted that required at least one retransmission.

## **tx**      **Send text message**

### **Syntax**

`Tx dst message <count>`

### **Example**

```
tx 1b hello 3  
Transmit DA 1B Data: hello
```

The `tx` (transmit) command is used to send a text message to a remote node. The target node is specified by the `<dst>` parameter, which should be a hexadecimal value between `0x01` and `0xFF` (broadcast to all nodes in range).

The `message` parameter is an arbitrary string of ASCII characters. To transmit messages with spaces, enclose the message in quotation marks (e.g., “message with spaces”). The `<count>` parameter is optional. If `<count>` is omitted, the message will be sent only once. If `<count>` is included, it must be between `0x00` and `0xFF`. A non-zero value means that the message will be sent `<count>` times. If `<count>` is zero, the message will be transmitted continuously. Continuous transmission terminates after the operator presses a key on the terminal program.

## *uecho*    **Set the UART in Echo or No Echo mode**

### **Syntax**

```
uecho <on|off>
```

### **Example 1**

```
uecho  
UART echo ON
```

### **Example 2**

```
uecho off  
UART echo OFF
```

The ZAURA RF Wireless Module Shell can be configured to echo characters received on UART0 Rx to UART0 Tx. This echo configuration allows the operator of the console terminal program to *see* the characters he or she is typing in the terminal window. However, the terminal program will also typically include a `local echo` option in which the terminal program automatically displays characters as they are entered in the terminal window. Configuring both the PC terminal program and the ZAURA RF Wireless node to echo UART data will result in two characters being displayed for every entered character, while disabling echo on both sides means that the operator will be typing blind.

The default ZAURA RF Wireless Module UART echo setting is controlled by the `ZAURA_RF_UartEcho` configuration variable. The value of this variable can be programmatically modified at run time; it can also be modified by using the `uecho` console command. If the `uecho` command is issued without any parameters, it will display the current UART echo state. To enable UART echo, issue the command `uecho on`. To disable UART echo, issue the command `uecho off`.

Each time the ZAURA RF Wireless nodes reset, UART echoing returns to the state defined by the `ZAURA_RF_UartEcho` configuration variable.

## **wake** Put the node in sleep mode after inactivity time out

- 
- ▶ **Note:** The `wake` command is not included in the ZAURA RF Shell Library. This command is defined in the ZAURA RF Demo project to demonstrate how a user-defined command can be integrated with ZAURA RF Shell commands. This command can only be used with the ZAURA RF Demo program.
- 

### **Syntax**

```
wake period <message> <target>
```

### **Example 1**

```
Wake
Wake period 10 seconds - Msg (len 5, dst FF):
'Hello'
```

### **Example 2**

```
wake 0
in active mode
```

### **Example 3**

```
Wake 3c Hello 1b
Wake period 60 seconds - Msg (len 5, dst 1B):
'Hello'
```

The default operating mode of the ZAURA RF Wireless Module demo project is to leave the radio constantly active in receive mode while waiting for console commands. The `wake` console command can be used to

force the device into a low power mode (see “sleep” on page 30) after a configurable inactivity time out. The ZAURA RF Wireless node will remain in the low power state until the operator presses the SW1 pushbutton or a character is entered in the terminal program.

If the ZAURA RF Wireless node is brought out of low power mode as a result of an SW1 action, it will optionally transmit a message to a target node(s). The message is not transmitted if the ZAURA RF Wireless node is brought out of low power mode due to console activity. After the ZAURA RF Wireless node is in the active state, it will start an inactivity timer. After this timer reaches `period` seconds, the device returns to low power mode. Each time console, SW1 or RF activity is detected while in active mode, the inactivity timer is reset to 0 to extend the duration of time that the unit will remain awake.

If the `wake` console command is issued without any parameters, the current wake settings are displayed. If a time-out period is specified without `<message>` and `<target>` parameters, the ZAURA RF Wireless node will enter low power mode after the specified time-out period expires and will not transmit a wake-up `<message>` when brought out of low power mode due to SW1 being pressed. If the `<message>` parameter is specified without a `<target>` parameter, the wake-up `<message>` is broadcast to all nodes when SW1 is pressed. Otherwise, the wake-up `<message>` is only sent to the `<target>` ZAURA RF Wireless node. Any time the time-out period, wake-up `<message>` or `<target>` values are modified, the demo program updates UserParams in Flash.

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